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Article

Challenges in Methane Column Retrievals from AVIRIS-NG Imagery over Spectrally Cluttered Surfaces: A Sensitivity Analysis

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Abstract: A comparison between efforts to detect methane anomalies by a simple band ratio approach from the Airborne Visual Infrared Imaging Spectrometer-Classic (AVIRIS-C) data for the Kern Front oil field, Central California, and the Coal Oil Point marine hydrocarbon seep field, offshore southern California, was conducted. The detection succeeded for the marine source and failed for the terrestrial source, despite these sources being of comparable strength. Scene differences were investigated in higher spectral and spatial resolution collected by the AVIRIS-C successor instrument, AVIRIS Next Generation (AVIRIS-NG), by a sensitivity study. Sensitivity to factors including water vapor, aerosol, planetary boundary layer (PBL) structure, illumination and viewing angle, and surface albedo clutter were explored. The study used the residual radiance method, with sensitivity derived from MODTRAN (MODerate resolution atmospheric correction TRANsmission) simulations of column methane (XCH₄). Simulations used the spectral specifications and geometries of AVIRIS-NG and were based on a uniform or an in situ vertical CH₄ profile, which was measured concurrent with the AVIRIS-NG data. Small but significant sensitivity was found for PBL structure and water vapor; however, highly non-linear, extremely strong sensitivity was found for surface albedo error. For example, a 10% decrease in the surface albedo corresponded to a 300% XCH₄ increase over background XCH₄ to compensate for the total signal, less so for stronger plumes. This strong non-linear sensitivity resulted from the high percentage of surface-reflected radiance in the airborne at-sensor total radiance. Coarse spectral resolution and feedback from interferences like water vapor underlay this sensitivity. Imaging spectrometry like AVIRIS and the Hyperspectral InfraRed Imager (HypIRI) candidate satellite mission, have the advantages of contextual spatial information and greater at-sensor total radiance. However, they also face challenges due to their relatively broad spectral resolution compared to trace gas specific orbital sensors, e.g., the Greenhouse gases Observing SATellite (GOSAT), which is especially applicable to trace gas retrievals over scenes with high spectral albedo variability. Results of the sensitivity analysis are applicable for the residual radiance method and CH₄ profiles used in the analysis, but they illustrate potential significant challenges in CH₄ retrievals using other approaches.

Keywords: methane; AVIRIS-NG; albedo sensitivity; spectral clutter; spatial heterogeneity; GOSAT; remote sensing

1. Introduction

1.1. Methane

The potent greenhouse gas (GHG), methane (CH₄) is the second most important anthropogenic gas affecting the global radiative balance after carbon dioxide (CO₂). CH₄ is 34 times stronger as

a heat-trapping gas than CO₂ on a 100-year timescale (86 times on a 20-year timescale) [1]. About 60–70% of global CH₄ emissions arise from anthropogenic sources including rice agriculture, fossil fuel industrial (FFI) production, waste handling, and domestic ruminants [2]. Important natural CH₄ sources include wetlands, termites, and geological seepage [3].

Given that CH₄'s atmospheric residence time is only ~8.5 years [4]—i.e., far shorter than the century timescale of CO₂, there are advantages to addressing global warming through CH₄ emission regulations compared to CO₂ [5]. Since pre-industrial times, CH₄ concentrations have risen, with the increase rate slowing and then almost stopping between 1999 and 2006, but growth has resumed since 2007 [6,7]. A number of mechanisms have been proposed to underlie these trends [6,8,9]; however, high uncertainty in emissions complicates interpretations. For example, a recent study suggested that FFI emissions are one and a half times greater than previous inventory estimates [10], while those of husbandry also appear to be underestimated significantly [11]. Given that accurate inventories are key to effective mitigation strategies, there is a critical need for new approaches to assess emissions to improve inventories.

The National Oceanic and Atmospheric Administration (NOAA) tower network provides in situ, highly accurate CH₄ measurements. Still, it cannot improve inventories at the regional (or national in many cases), local, or facility scale due to the scarcity of the observing stations [12]. In contrast, satellites provide global coverage and repeat measurements at high data density allowing effective monitoring of CH₄ concentrations at regional to local scales, if the sensor has sufficient resolution [13]. Necessarily, retrieval algorithm validation for current and future satellite missions is required to enable satellite data to improve inventories. Airborne remote sensing data can play a critical validation role.

1.2. Methane Remote Sensing

Only satellite remote sensing provides the global coverage to address emissions on the global scale needed to address factors underlying greenhouse warming. The first global map of tropospheric CH₄ was provided by the SCanning Imaging Absorption spectroMeter for Atmospheric CHartographyY (SCIAMACHY) instrument launched in 2002 [14], which operated through 2012 at a 30 × 60 km resolution. More recently, the currently operational Greenhouse gases Observing SATellite (GOSAT) operated by Japan Aerospace Exploration Agency (JAXA), provides global column CH₄ (XCH₄, see definition in Table 1) by means of proxy and physics-based algorithms [15–17]. GOSAT observes at 10 × 10 km spatial resolution and is a sampling mission. The Thermal And Near infrared Sensor for carbon Observation (TANSO)—Fourier Transform Spectrometer (FTS) onboard GOSAT uses spectral absorption features near 1.6 μm for CH₄ retrieval with 0.2 cm⁻¹ spectral intervals and 0.27 cm⁻¹ spectral resolution. The coarse spatial resolution of these satellite instruments (and sampling nature of GOSAT) challenges facility-level monitoring sources with their data. The Sentinel 5 precursor mission, TROPOspheric Monitoring Instrument (TROPOMI), is scheduled to launch in 2017 with a 7 km spatial resolution, followed by the Sentinel 5 mission in 2021, to provide daily global mapping coverage of XCH₄ and XCO₂ [18].

Existing airborne systems can remotely sense CH₄ at finer than satellite scales, using either non-imaging or imaging spectrometers. Airborne non-imaging sensors have higher sensitivity to CH₄, an example being the Methane Airborne MAPper (MAMAP) sensor [19], whereas imaging sensors have lower sensitivity, but include contextual information, examples being the instrument Mako [20] and HyTes [21] that use the thermal infrared (TIR), and Airborne Visual InfraRed Imaging Spectrometer-Classic (AVIRIS-C) [22] and AVIRIS-Next generation (AVIRIS-NG) [23] spectrometers that use the short-wave infrared (SWIR). AVIRIS-C and AVIRIS-NG specifications are provided in Section 2.1.

A number of approaches have been developed to retrieve XCH₄ from airborne and satellite data. These approaches include qualitative ones such as band-ratio approach [24], cluster-tuned matched filter (CTMF) approach [25], and quantitative ones such as the Weighting Function Modified (WFM) Differential Optical Absorption Spectroscopy (DOAS) algorithm [14], and the Iteratively Maximum a Posteriori DOAS (IMAP-DOAS) algorithm [26].

Table 1. Nomenclature.

Symbol	Definition	Unit
<i>Ar</i>	Asphalt road	N/A
<i>Bsl</i>	Brown sandy loam	N/A
<i>Rbl</i>	Reddish-brown fine sandy loam	N/A
GOSAT	Greenhouse gases Observing SATellite	N/A
<i>i</i>	Band number	N/A
<i>k</i>	Scaling factor for XCH _{4_p}	N/A
$L_t(\alpha, \lambda)$	at-sensor radiance in wavelength λ for a q_s relative error of α	mW cm ⁻² μ m ⁻¹ sr ⁻¹
$S(XCH_{4_b}, \alpha)$	Albedo sensitivity with a scenario, XCH _{4_b} and the relative error, α , in q_s	dimensionless
XCH ₄	Methane column ratio	ppm
XCH _{4_A}	Background methane column ratio	ppm
XCH _{4_P}	Plume methane column ratio	ppm
XCH _{4_b}	Base XCH ₄	ppm
XCH _{4_err}	XCH ₄ from trial and error	ppm
XCH _{4_GOSAT}	Mean XCH ₄ over subpixels in GOSAT pixel	ppm
θ_s	Solar zenith angle	degree
θ_v	Viewing zenith angle	degree
ϕ	Relative sun-sensor azimuth angle	degree
λ	Wavelength	nm
$q_s(\lambda)$	Surface albedo	dimensionless
$q_t(\lambda)$	At-sensor reflectance	dimensionless
$L_t(\lambda)$	At-sensor radiance	mW cm ⁻² μ m ⁻¹ sr ⁻¹
$L_{t_GOSAT}(\lambda)$	Mean $L_t(\lambda)$ over subpixels in GOSAT pixel	mW cm ⁻² μ m ⁻¹ sr ⁻¹
$L_{t_AO}(\lambda)$	Mean L_t over the subpixels	mW cm ⁻² μ m ⁻¹ sr ⁻¹
$L_{t_OA}(\lambda)$	L_t for the mean surface albedo over subpixels	mW cm ⁻² μ m ⁻¹ sr ⁻¹
L_{t_err}	L_t for the original albedo and XCH ₄ with 10% underestimation	mW cm ⁻² μ m ⁻¹ sr ⁻¹
q_{s_err}	q_s corresponding to L_{t_err} and the original XCH ₄	dimensionless
XCH _{4_M}	XCH ₄ corresponding to L_{t_GOSAT} and mean albedo over GOSAT subpixels	ppm
NE δ L	Noise equivalent delta radiance	mW cm ⁻² μ m ⁻¹ sr ⁻¹
NE δ L _a	NE δ L adjusted to the band average	mW cm ⁻² μ m ⁻¹ sr ⁻¹
α	Relative error in surface albedo	%
β	Relative error in L_t	%
γ	Underestimate of XCH ₄ resulted from the subpixel heterogeneity of CH ₄	ppm
σ	$q_t(2298)/q_t(2058)$	dimensionless
Δ	Average residual radiance	mW cm ⁻² μ m ⁻¹ sr ⁻¹
Pc	Percentage of area in one GOSAT pixel covered by XCH ₄ plume	%

1.3. Study Motivation

Real-world applications of radiative transfer models to atmospheric simulations almost always incorporate imperfect information given that in situ profile data and surface spectral data generally are unavailable. Imperfect information propagates into biases in the trace gas retrievals. This study is developed out of a scoping study that compared XCH₄ for two scenes of comparable emission strength, one marine and one terrestrial—i.e., different radiative transfer characteristics and surface spectral complexity. The scoping study used a simple band-ratio method [24], which is computationally fast and can screen large datasets to identify spatial subsets for more sophisticated analysis. Specifically, the scoping study analyzed AVIRIS-C acquired 19 June 2008 for the Coal Oil Point (COP) marine seep field and 6 June 2013 for the Kern Front oil field (terrestrial) (Figure 1). This is a producing oil field and is located near Bakersfield, California, in the central San Joaquin Valley, California. Emissions have been estimated at $\sim 1.0\text{--}1.5 \times 10^5$ m³ day⁻¹ (25 Gg year⁻¹) [27] for the COP seep field. Emissions for the Kern Front oil field were estimated at ~ 60 Gg year⁻¹ in September 2014, decreasing exponentially to ~ 30 Gg year⁻¹ by late 2015 [28].

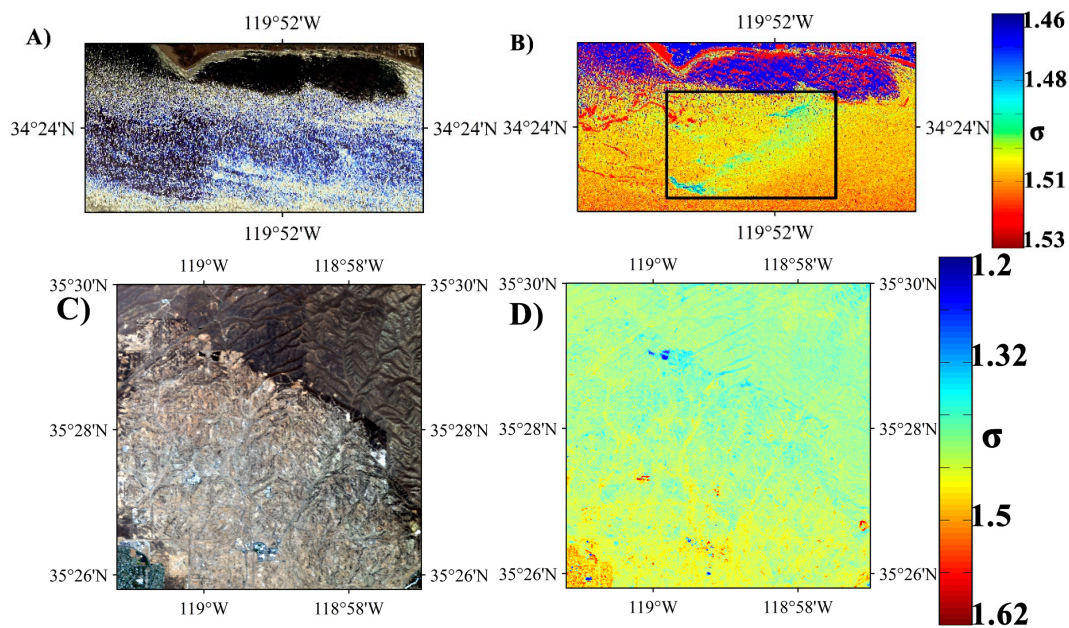


Figure 1. (A) True color imagery of Airborne Visual Infrared Imaging Spectrometer-Classic (AVIRIS-C) data acquired on 19 June 2008. (B) Band ratio (σ) of at-sensor reflectance (ρ_t) for the 2298 and 2058 nm bands, $\sigma = \rho_t(2298)/\rho_t(2058)$ for AVIRIS-C data in (A), black rectangle outline shows clear plume structure. (C) True color imagery of AVIRIS-C data acquired on 6 June 2013. (D) σ for AVIRIS-C data in (C). Data key on figure.

The scoping study revealed a dramatic performance difference for XCH_4 retrievals (Figure 1). Strong CH_4 plumes were easily detected for the marine source, but were highly challenged for the terrestrial source. The main purpose of the present study was to better understand these differences through a series of sensitivity studies testing different factors that could influence the XCH_4 retrievals including albedo, water vapor, observational geometry, aerosol, and surface spectral heterogeneity. Findings are evaluated with respect to implications for airborne and spaceborne remote sensing sensors. Sensitivity was studied through forward modeling using MODTRAN, the spectral specifications and geometries of AVIRIS Next Generation (AVIRIS-NG), and the residual radiance, also termed the residual radiance method. The residual radiance method has been used for successful trace gas detection of the offshore emissions from the COP seep field [29]. For simplicity, the modeling is for a uniform surface, despite the fact that in reality many surfaces can exhibit complicated effects in their Bi-directional Reflectance Distribution Functions (BRDF). The study focused on understanding factors leading to the band ratio's poor performance for the Kern oil fields and how they also impact a more sophisticated approach, the residual radiance method. These sensitivity study results are directly applicable only to the residual radiance method for XCH_4 retrievals. Still, the findings have implications for other retrieval methods due to common radiative transfer challenges, such as spectral clutter, particularly for moderate spectral resolution instruments.

2. Materials and Methods

2.1. Imaging Spectrometers

AVIRIS-C is a whiskbroom sensor that collects radiance from 380 to 2500 nm in 224 channels with a ~ 10 nm bandwidth and 1 milliradian [30]. AVIRIS-NG is the successor instrument to AVIRIS-C and is a pushbroom sensor that collects spectra in 432 bands at a sampling interval of 5 nm and a Full Width at Half Maximum (FWHM) varying from 5.6 to 6.0 nm. AVIRIS-NG has improved geo-location and signal to noise ratio (SNR) over AVIRIS-C (SNR > 1000 @ 600 nm and > 800 @ 2200 nm, at an input reflectance

level of 25%) [31]. A Gaussian function was employed to describe the slit function. The cross-track swaths of the AVIRIS-C and AVIRIS-NG are 892 and 795 pixels, respectively, with an angular swath width of 30° .

Dennison et al. [32] reported that the $NE\delta L$ of AVIRIS-NG is one third that of AVIRIS-C, which Green & Pavri [33] estimated at $0.001 \text{ mW cm}^{-2} \mu\text{m}^{-1} \text{ sr}^{-1}$. For this study, the $NE\delta L$ is taken as $0.00035 \text{ mW cm}^{-2} \mu\text{m}^{-1} \text{ sr}^{-1}$ for AVIRIS-NG. Important geometric parameters include solar zenith angle (θ_s), sensor viewing zenith angle (θ_v) and relative sun-sensor azimuth angle (ϕ). Jet Propulsion Laboratory provided geo-referenced radiance data and observation geometries.

2.2. Study Area

The sensitivity study used the observation geometry, surface albedo from AVIRIS-NG imagery acquired for the Kern River oil field (Figure 2), located immediately north of Bakersfield, CA. CH_4 leakage plumes have been documented by remote sensing for this active oil field [20], as well as by in situ observations [28].

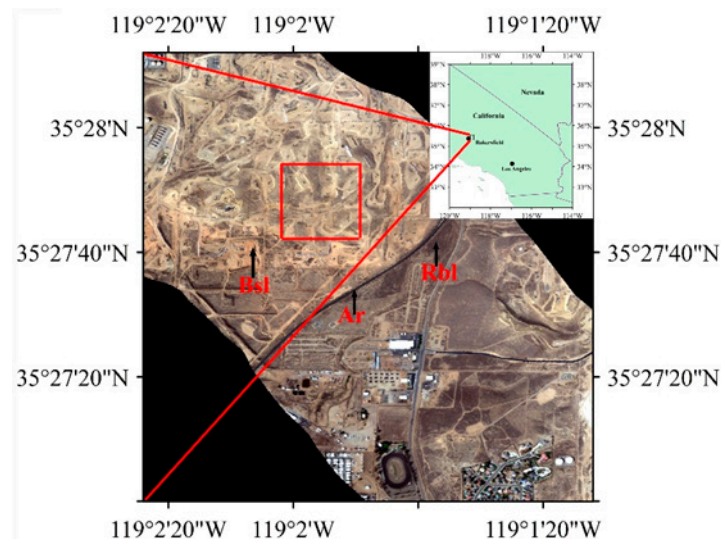


Figure 2. True color imagery for AVIRIS-NG image of the Kern Front oil field, near Bakersfield, central California on 4 September 2014. The land cover types for the three pixels selected for sensitivity analysis are noted, by Ar, Bsl, and Rbl, which are for Asphalt road, Brown sandy loam, and Reddish brown sandy loam, respectively. Pixels in the red box are used to investigate the effect of subpixel heterogeneity on albedo and XCH_4 .

Supporting this study are data collected during the CO_2 and Methane EXperiment (COMEX) [34]. COMEX combined in situ airborne and surface data, with airborne imaging and non-imaging spectroscopy to explore synergies between these remote sensing approaches for GHG emission estimation. COMEX investigated southern California CH_4 sources including husbandry, landfills, natural geology, and FFI refining and production, the latter being the strongest among the COMEX foci.

This study leveraged the availability of simultaneous in situ profile and AVIRIS-NG data, to understand the impact of erroneous vertical CH_4 profile on XCH_4 . Two profile cases were simulated, in situ profile and a uniform profile (see Figure 3B). The two profiles have the same column-averaged CH_4 within a boundary layer of 2.0 km. In situ data were collected in a data curtain (Figures 3A and A1) by the CIRPAS Twin Otter airplane (www.cirpas.org) above the Kern Front oil field [19].

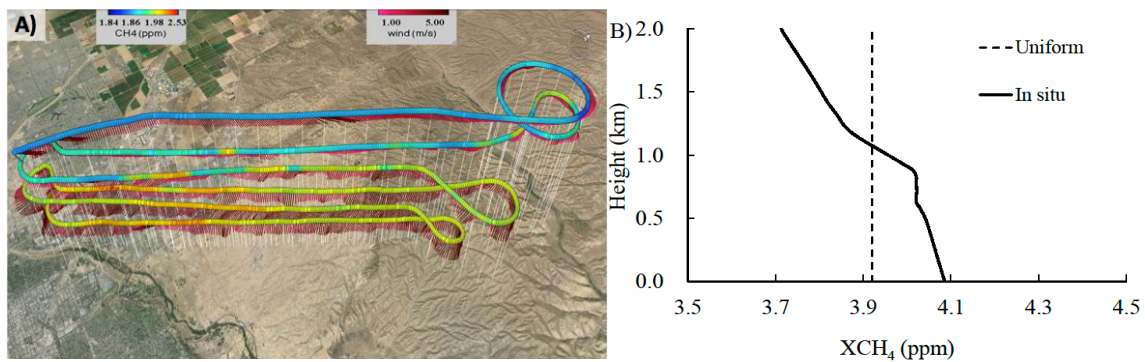


Figure 3. (A) In situ methane, CH_4 , and wind data for 4 September 2014 collected by CIRPAS for the Kern Front and Kern River oil fields. Data key on panel. (B) Derived in situ and uniform CH_4 profiles, which have the same column-averaged CH_4 within a boundary layer of 2.0 km.

The CIRPAS acquisition was concurrent (to a few hours) with the AVIRIS-NG acquisition. In situ CH_4 concentrations were measured by an onboard Cavity Ringdown Spectrometer (Picarro Inc., Mountainview, CA, USA). Data in the survey plane were segregated as in the plume or outside, averaged at each altitude level, and then interpolated linearly between levels. Data identified the Planetary Boundary Layer (PBL) at ~ 1.2 km (Figures 3B and A2). Additional details on the measurement and derivation of the in situ profile are provided in Appendix A.1. The “uniform profile” presumed a well-mixed atmosphere (vertically uniform) to 2.0 km altitude. For all two cases, the profile above 2.0 km was that of a typical mid-latitude summer atmosphere.

2.3. Radiative Transfer Simulations—Residual Radiance Method

MODTRAN has a long history of being applied to trace gas retrievals, e.g., Roberts et al. [29] and Thorpe et al. [25]. In this study, we use MODTRAN5.3.2 to model L_t for the AVIRIS-NG sensor viewing and illumination geometries and bandwidth (5 nm). Gaussian slit functions were used in the simulations. Two plume simulation scenarios were considered, a uniform profile and an in situ profile (Section 2.2). The atmosphere simulated was a typical mid-latitude summer atmosphere. Thus, the default mid-latitude CH_4 profile was used for above 2.0 km. Visibility was derived from the atmospheric correction of AVIRIS-NG using the Fast Line-of-sight Atmospheric Analysis of Spectral Hypercubes (FLAASH) module in Environment for Visualizing Images (ENVI) for an urban aerosol. Water vapor column was derived from the water absorption feature that overlaps the 1135 nm band. AVIRIS-NG data provided the land cover spectra and observation geometries for the sensitivity analysis.

The residual radiance method for CH_4 retrieval is detailed in Roberts et al. [29], and summarized briefly below. In this study, the method was used in forward modeling to evaluate whether two modeled total radiance spectra (using different input parameters) agreed with each other. First, the at-sensor radiance (L_t) was simulated for a surface albedo (ρ_s) of 0.1 and the aerosol and water vapor derived using the method described above. The true ρ_s was approximated by comparing the simulated L_t with the observed L_t for 2139 nm, under the assumption that L_t increases linearly with ρ_s . The 2139 nm band was used to estimate ρ_s because it is the band closest to the CH_4 spectral absorption feature (2239–2299 nm) that also is free of CH_4 absorption (Figure 4A). ρ_s in the wavelength range of 2239–2299 nm was assumed to be equal to ρ_s for 2139 nm—a spectral flatness assumption. Spectral flatness may not be a valid assumption for some land surface types, introducing biases in $X\text{CH}_4$. A new radiative transfer simulation was carried out using the newly calculated ρ_s and a background $X\text{CH}_4$, from which a new set of L_t were derived. The average residual radiance (Δ) was calculated by averaging the subtraction of the AVIRIS-NG observed L_t from the simulated L_t (denoted by $L_{t\text{sim}}$) for bands from 2239 to 2299 nm, where CH_4 had stronger absorption than water vapor (Figure 4B).

$$\Delta = \frac{1}{N} \sum_{i=1}^N (L_{t_{sim}}(\lambda_i) - L_t(\lambda_i)) \quad (1)$$

Note, a large Δ corresponds to high CH_4 absorption—i.e., high XCH_4 . It should be noted that the residual radiance method for XCH_4 retrieval was presented in this paper by forward simulations for calculating residual radiance that was used to derive the sensitivity.

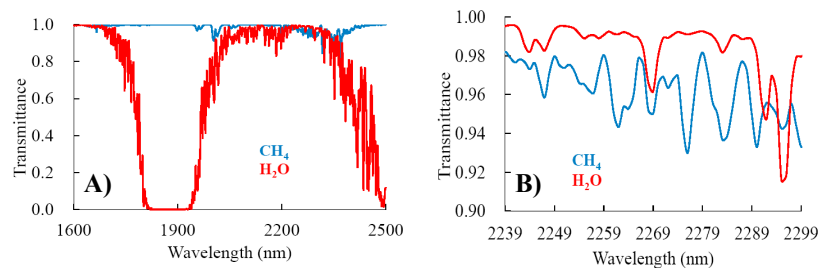


Figure 4. Transmittance spectra for H_2O and CH_4 in wavelength ranges of (A) 1600–2500 nm, (B) 2239–2299 nm, generated using MODerate resolution atmospheric correction TRANsmision (MODTRAN) for a mid-latitude summer atmosphere for the AVIRIS-NG sensor (Figure 2) at 2.4 km altitude with CH_4 based on in situ data, see Figure 3.

2.4. Sensitivity Studies

The sensitivity of XCH_4 to surface albedo was based on the hypothesis that errors in surface albedo propagate through the MODTRAN calculations manifesting as an error in XCH_4 that produces the same measured L_t . Because of the underlying key importance of surface albedo, sensitivity studies were referenced to the spectra of three common scene elements in the Kern Front oil field imagery: Asphalt road, Brown sandy loam, and Reddish-brown sandy loam, noted as Ar, Bsl, and Rbl, respectively (Figure 5). These three scene elements span a range of occurrence probabilities in the AVIRIS-NG imagery, with Rbl being dominant (Figure A3 in Appendix A.2). The three surface types differ in terms of both magnitude and shape of the spectral reflectance, which deviate slightly from a spectrally flat behavior (see Figure 5B).

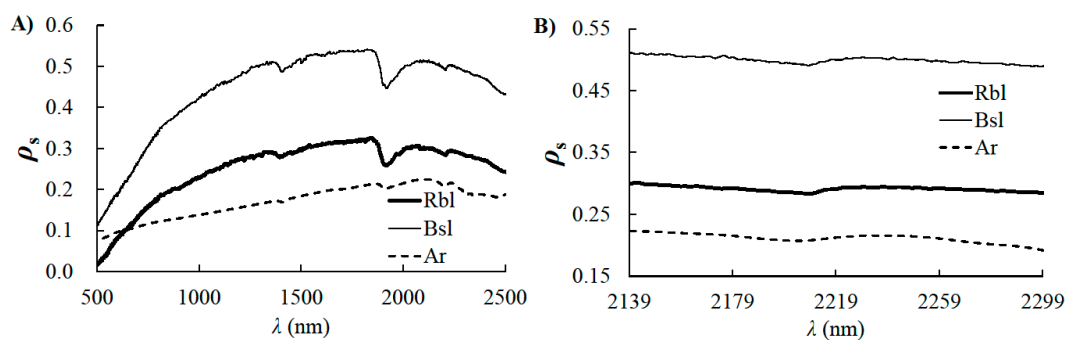


Figure 5. Surface albedo (ρ_s) for (A) 500 to 2500 nm, (B) 2139 to 2299 nm, for three common scene elements: asphalt road (Ar), brown sandy loam (Bsl), and red-brown sandy loam (Rbl), respectively. Data key on figure. Spectra are from Environment for Visualizing Images (ENVI) library.

Within the CH_4 absorption feature, increases (decreases) in XCH_4 will decrease (increase) L_t . Thus, inaccurate ρ_s biases XCH_4 . The retrieved XCH_4 sensitivity to ρ_s was evaluated through MODTRAN simulations for a XCH_4 “base-scenario”, denoted XCH_{4_b} , with respect to relative error in ρ_s , denoted α , which spanned from -50% to 50% . $L_t(\lambda_i)$ for different values of α was derived for the 13 AVIRIS-NG bands from 2239 to 2299 nm, denoted $L_t(\alpha, \lambda_i)$. Using the original ρ_s , the increase (for $\alpha < 0$) or decrease

(for $\alpha > 0$) in XCH_4 relative to XCH_{4_b} was determined by error minimization, which minimized the average residual radiance (Δ) until convergence, defined as $\Delta < NE\delta L_a$, where $NE\delta L_a$ is the average over the N bands spanning the feature, i.e.,

$$\Delta = \frac{1}{N} \sum_{i=1}^N |L_t(0, \lambda_i) - L_t(\alpha, \lambda_i)| \quad (2)$$

$$NE\delta L_a = \frac{NE\delta L}{\sqrt{N}} \quad (3)$$

where N is 13, and i is the band number. For convenience, we denoted XCH_{4_err} for the residual-radiance minimized XCH_4 for q_s with respect to α . Finally, we defined the sensitivity to α for the CH_4 column, $S(XCH_{4_b}, \alpha)$:

$$S(XCH_{4_b}, \alpha) = \frac{XCH_{4_err} - XCH_{4_b}}{XCH_{4_b}} \quad (4)$$

A negative (positive) α means underestimation (overestimation), which causes an overestimation (underestimation) of XCH_4 and as a result $S(XCH_{4_b}, \alpha)$ is positive (negative).

Taking a negative α as an example, the error minimization was carried out as follows. XCH_4 is increased from XCH_{4_b} by a specified interval (e.g., 0.01 ppm). For each increase, L_t was simulated and applied to Equation (2) to calculate Δ . The increase continues until Δ in Equation (2) is smaller than $NE\delta L_a$.

Using the same method for deriving the sensitivity to albedo as described above, sensitivities to water vapor and to spectral flatness were also investigated. The sensitivity to scene geometry (or aerosol, vertical profile) was derived by calculating $S(XCH_{4_b}, \alpha)$ using the method described above for different geometries (or aerosols, vertical profiles) while other parameters were kept unchanged.

3. Results

3.1. Sensitivity Studies

The sensitivity study investigated the relative importance of the various differing factors between the scenes to understand the relative importance of the factors underlying the difference between the band ratio analysis of the Kern versus the COP scenes. Sensitivity studies are for the residual radiance method. Factors include surface albedo, vertical profile, scene geometry, spectra flatness, water vapor, and aerosols.

3.1.1. Sensitivity to Albedo Error

The simulations showed that XCH_4 exhibited an extremely strong and non-linear sensitivity to q_s error (α), with the relative error in $L_t(\lambda)$ (β) for the plume simulation exhibiting a significant but linear sensitivity—note how $\beta(\alpha)$ lies on the 1:1 line (Figure 6A). The albedo error sensitivity with respect to XCH_4 was explored by varying the plume strength from $k = 0$ (background, XCH_{4_A}) to $k = 1$ (in situ profile) to $k = 10$ (factor of 10 stronger plume than observed), i.e.,

$$XCH_4 = XCH_{4_A} + k \times XCH_{4_P} \quad (5)$$

Here, XCH_{4_P} is the plume anomaly, such that $XCH_{4_A} + XCH_{4_P}$ is the vertical plume profile. Simulations revealed a significant and non-linear XCH_4 error resulted from the error in q_s for the observed plume ($k = 1$), a sensitivity that was close to invariant with land cover types (Figure 6B). This albedo error sensitivity in XCH_4 was explored further for the dominant scene element, Rbl by varying the plume anomaly strength from $k = 0$ to $k = 10$ (Figure 6C). $S(XCH_{4_b}, \alpha)$, is highly nonlinear (Figure 6C), albeit less so for stronger plumes ($k > 1$). For example, for $\alpha = -5\%$ for pixel Rbl, S decreased from 144.3% to 18.5% for XCH_4 increasing from background ($k = 0$) to a very strong plume

($k = 10$). XCH_4 could not be retrieved for α higher than 5% for XCH_4 plumes of $k = 0, 0.1, 0.25$. For the $k = 10$ plume, XCH_4 could not be retrieved for α higher than 45%. This means no XCH_4 could be found that would meet the convergence requirements of Equations (2) and (3).

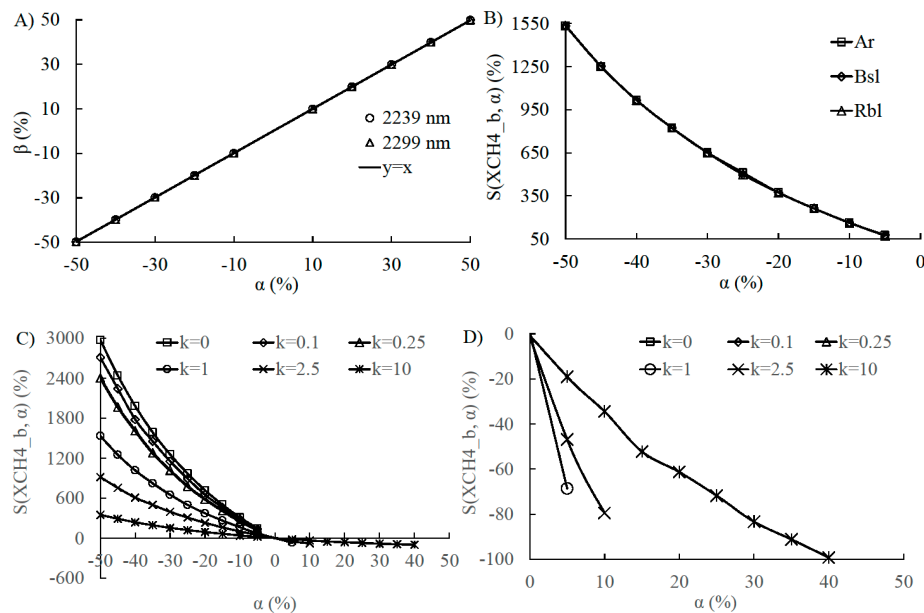


Figure 6. (A) Relative error (β) in at sensor radiance ($L_t(\lambda)$) with respect to the relative surface albedo error (α) and 1:1 line (solid). (B) Relative methane column, XCH_4 , sensitivity, $S(XCH_4_b, \alpha)$ with respect to α for the three land cover types, Ar, Bsl, Rbl, which are for Asphalt road, Brown sandy loam, and Reddish brown sandy loam, respectively. XCH_4_b is for the observed plume ($k = 1$) in all simulations. (C) $S(XCH_4_b, \alpha)$ for pixel Rbl with different plume strength cases defined by k , see Equation (4). (D) Expanded view of (C) for positive α .

$S(XCH_4_b, \alpha)$ is much larger for small plumes than for strong plumes, as shown in Figure 6C, simply because approximately the same amount of XCH_4 must compensate for the same albedo error, but that this constant amount is divided by a smaller or a larger value of XCH_4 (see Figure 7).

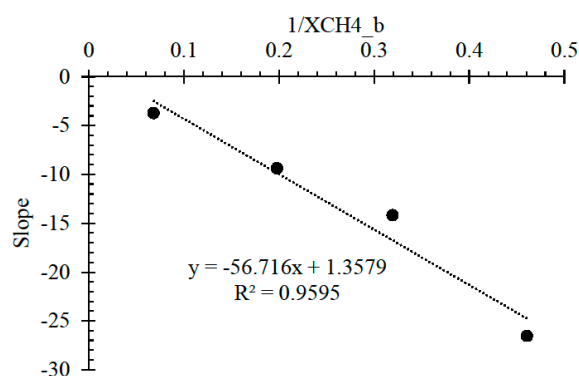


Figure 7. Inverse XCH_4_b ($1/XCH_4_b$) versus slope of the lines in Figure 6C, calculated for data near $\alpha = 0$ for the plume strength cases of $k = 0.25, 1, 2.5$, and 10 .

3.1.2. Variation of Albedo Sensitivity with Vertical CH_4 Profile

Comparison between the simulations showed that the measured profile, with a shallower PBL, reduced sensitivity ($S(XCH_4_b, \alpha)$) by 9–12% compared to a uniform profile (Figure 8). The sensitivity difference resulting from the difference in vertical CH_4 distribution indicated that path dependency

was a factor that should be considered in the CH₄ retrieval. This showed that at a minimum, the importance of using appropriate PBL thicknesses for retrievals in different regions, using realistic profiles, if available, is naturally the best option.

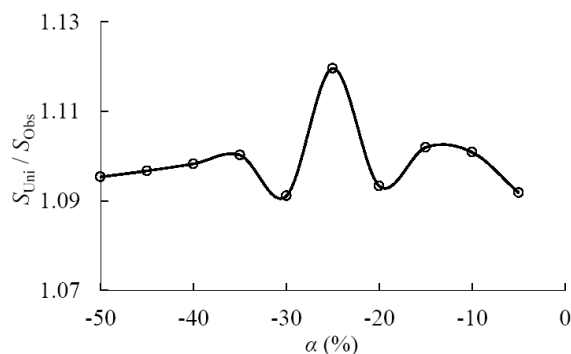


Figure 8. Introduced relative error (S_{Uni}/S_{Obs}), for two scenarios, a uniform 2.0 km planetary boundary layer (PBL) (S_{Uni}) relative to the observed profile (S_{Obs}) shown in Figure 3. Both scenarios have the same XCH₄.

3.1.3. Variation of Albedo Sensitivity with Scene Geometry

Scene geometry sensitivity was investigated by simulations for the $k = 1$ plume, with solar zenith angle (θ_s) varied from 30° to 50°, sensor viewing zenith angle (θ_v) varied from 0° to 20°, and relative sun-sensor azimuth angle (ϕ) varied from 0° to 180°. With respect to observation geometry, $S(XCH_{4_b}, \alpha)$ exhibits the strongest angular sensitivity to θ_s (Figure 9A), with little difference between scene elements. $S(XCH_{4_b}, \alpha)$ is related inversely to increases in θ_s and θ_v but is constant with ϕ due to the simulations' Lambertian surface characterization (Figure 9). The relatively strong angular sensitivity to θ_s and θ_v is probably due to that the relative contribution from the surface scattering versus from atmospheric scattering decreases with increasing θ_s or θ_v .

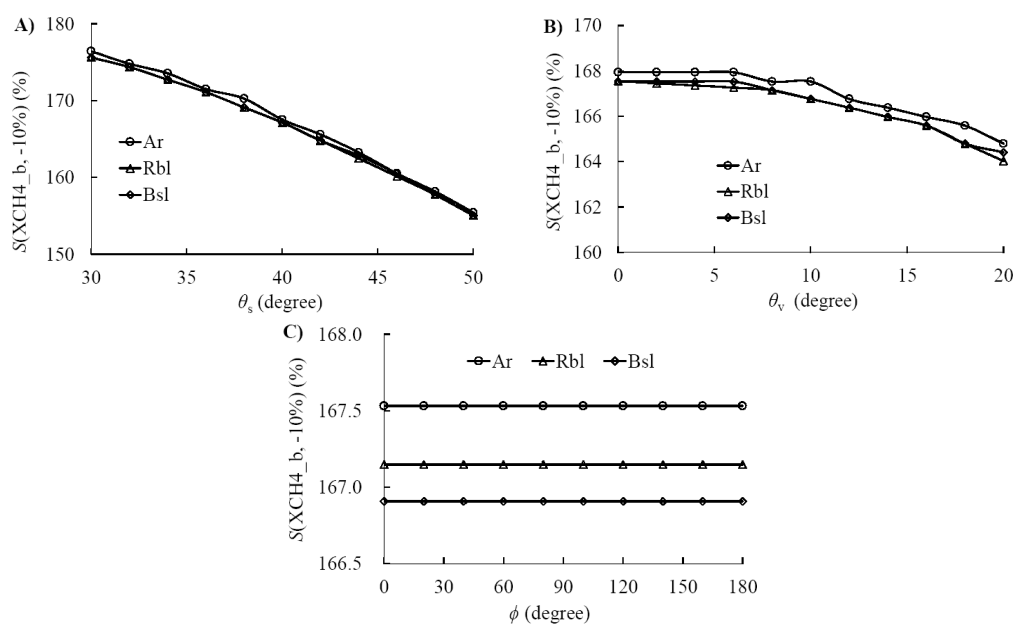


Figure 9. Column retrieval error ($S(k = 1, \alpha = -10\%)$) where $k = 1$ signifies the plume profile (Figure 3) for (A) solar zenith angle (θ_s) when viewing zenith angle (θ_v) and relative sun-sensor azimuth angle (ϕ) are equal to 8°, 90° respectively, (B) θ_v when θ_s and ϕ are equal to 40°, 90° respectively, and (C) ϕ when θ_s and θ_v are equal to 40°, 8° respectively.

3.1.4. Variation of Albedo Sensitivity with Aerosol Type and Visibility

Given the similarity in $S(XCH_{4_b}, \alpha)$ between surface spectral composition for the parameters studied, aerosol sensitivity was studied only for Rbl pixel and showed no significant difference in $S(XCH_{4_b}, \alpha)$ between the two highly distinct aerosol types considered, urban and marine (Figure 10)—163% vs. 160% for urban compared to the marine atmosphere. Thus, the discrepancy between clearly detected plumes in the marine environment (Figure 1B) and no detectable plumes for the urban terrestrial environment (Figure 1D) was not due to the significant differences between marine and terrestrial aerosol. The overestimation changed from 160.8% for a 16-km visibility to 157.7% for 2-km visibility.

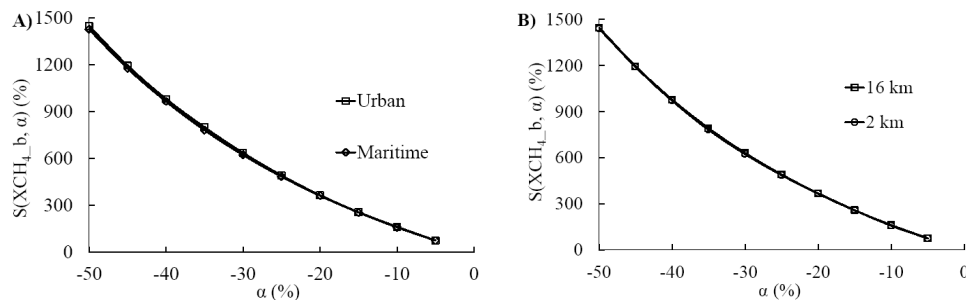


Figure 10. Column retrieval error ($S(XCH_{4_b}, \alpha)$) versus α for XCH_{4_b} of plume case $k = 1$ for (A) different aerosol type, (B) different visibility.

3.1.5. Sensitivity to Spectral Flatness

The residual radiance method [29] has an underlying important spectral flatness assumption. In reality, $q_s(\lambda)$ varies with λ for a water surface in the spectral range of the CH_4 absorption feature, decreasing from 2139 to 2299 nm. Simulations showed that the flat spectra assumption led to an overestimation of the calculated L_t compared with the true albedo spectra (Figure 11). The overestimation in L_t increased with, longer λ and resulted in a non-negligible underestimation of XCH_4 . Table 2 further quantified this underestimation, which decreased with brighter surface pixels. Furthermore, this underestimation in L_t increased with a decrease in XCH_{4_b} . In fact, for the background ($k = 0$), XCH_4 could not be retrieved for the pixel Ar with XCH_{4_A} for the constant surface albedo assumption based on albedo at 2139 nm (Table 2). The underestimation decreased to 30% for Ar and to 8.1% for Bsl as XCH_4 increased from background to the $k = 1$ plume.

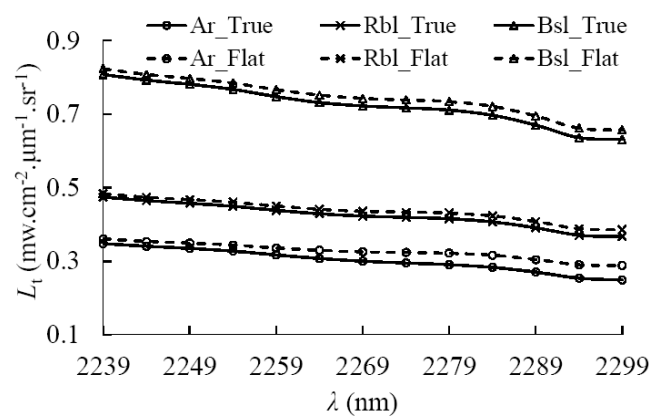


Figure 11. Calculated sensor radiance (L_t) with respect to wavelength (λ) simulated for background XCH_4 . Solid lines show L_t for the true $q_s(\lambda)$ (denoted “_True”) for spectra for scene elements Asphalt road (Ar), Brown sandy loam (Bsl), and Reddish-brown fine sandy loam (Rbl) shown in Figure 3. Dashed lines show L_t for constant $q_s(2139)$ across the feature (denoted “_Flat”).

Table 2. $S(XCH_4_{b, \alpha = 0})$ resulting from constant q_s assumption for wavelengths 2239 to 2299 nm.

$XCH_4_{b, \alpha = 0}$	Underestimation (%)		
	Ar	Rbl	Bsl
$k = 0$	-	-79.77	-73.72
$k = 0.1$	-120.73	-70.35	-63.97
$k = 1$	-79.68	-35.81	-30.95
$k = 10$	-30.18	-10.65	-8.08

3.1.6. Sensitivity to Water Vapor

Water vapor was retrieved from Moderate Resolution Imaging Spectroradiometer (MODIS) data using a ratio of radiance in a band with water vapor absorption (905 or 940 nm) to that in a band free of the absorption (865 nm). The retrieved water vapor has been validated by in situ data, with a relative error estimated at ~7% [35]. In a study by Albert et al. [36], MODIS retrieved water vapor by means of a differential absorption technique was compared with the field measurements taken by microwave water radiometer. A relative deviation of 9.4% was derived from the comparison.

A sensitivity study based on a 9% uncertainty in AVIRIS-NG, water vapor retrievals (Figure 12) showed a detectable $S(XCH_4_{b, \alpha = 0})$ overestimation. Specifically, $S(XCH_4_{b, \alpha = 0})$ increased with the increase of water vapor while it decreased with increasing XCH_4 . Overall, $S(XCH_4_{b, \alpha = 0})$ varied little with the land cover types.

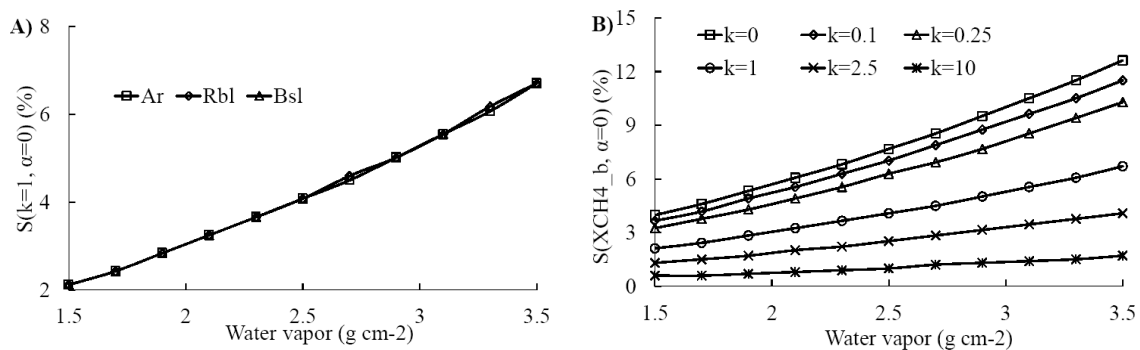


Figure 12. $S(XCH_4_{b, \alpha = 0})$ resulting from an overestimation of 9% in water vapor for (A) three pixels types, Asphalt road (Ar), Brown sandy loam (Bsl), and Reddish-brown sandy loam (Rbl) with the XCH_4 plume case, defined as $k = 1$, and (B) the pixel Ar for different XCH_4 plume strengths $k = 0, 0.1, 0.25, 1, 2.5, 10$. $k = 0$ represents background.

3.2. Space-Based Retrieval Sensitivity to Subpixel Spectral and CH_4 Heterogeneity

To investigate the sensitivity of XCH_4 to subpixel spectral heterogeneity, simulations were conducted for a simplified GOSAT pixel—a 10×10 km square (rather than round)—for 666 km altitude. The GOSAT pixel was divided into 160×160 subpixels with spatial resolution of 62.5 m, approximately the spatial resolution of the Hyperspectral Infrared Imager (HypSPIRI) mission, which has a planned 10-nm spectral resolution [37]. For this simulation, the albedos of a 100 km^2 subset of the AVIRIS-NG data, subset into 160×160 pixels, was derived from imagery acquired on 4 September 2014 (Figure 2, red box). Note, concurrent GOSAT data were unavailable for the Kern area on 4 September 2014.

L_t for the GOSAT pixel was simulated for the in situ profile (i.e., $k = 1$, Figure 3) by two approaches. In the first case, denoted L_{t_AO} , L_t was simulated for each of the 160×160 pixels using each pixel's q_s , and the orbital L_t then was averaged to produce the GOSAT pixel L_t . In the second case, denoted L_{t_OA} , the average q_s for the 160×160 pixels was calculated first, from which the GOSAT pixel L_t then was derived. The notation reflected whether spatial averaging occurred before or after extending

AVIRIS-NG ρ_s to the orbital sensor, respectively. The calculated L_{t_AO} and L_{t_OA} across the spectral area of interest were essentially identical (Figure 13), demonstrating linearity for the response of L_t to ρ_s .

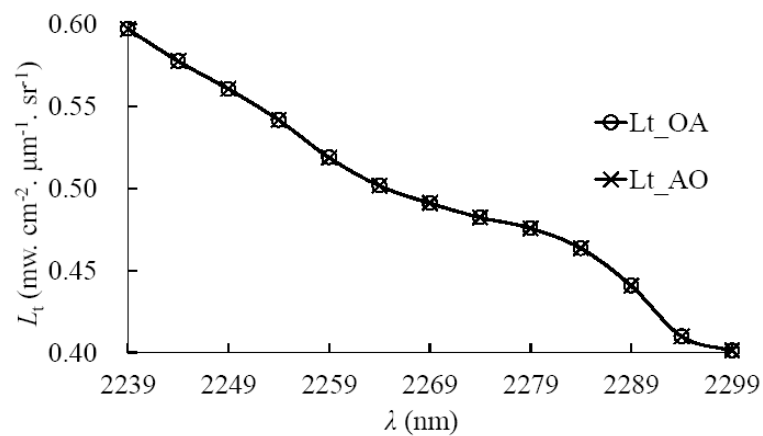


Figure 13. L_{t_OA} derived by averaging L_t simulated over each subpixel (a total of 160×160 subpixels), see text for description. L_{t_AO} simulated using the average albedo of the 160×160 subpixels. GOSAT pixel noted above. In situ profile (i.e., $k = 1$, Figure 3) was used for calculating L_{t_OA} and L_{t_AO} .

Although in some conditions, e.g., a well-mixed background PBL, GOSAT pixels were approximated reasonably well on the sub-pixel level as having homogeneous XCH_4 ; for many GOSAT pixels, XCH_4 was spatially heterogeneous. On the GOSAT size-scale, this heterogeneity was dominated by the overall plume dimensions; however, even on the vastly finer AVIRIS-NG size scale, strong heterogeneity exists due to plume structure, including puffiness [23].

The importance of spatial XCH_4 heterogeneity was investigated by simulations over a pixel of the same size as GOSAT, which was divided into 160×160 subpixels with a spatial resolution of 62.5 m. The L_t and albedo for these subpixels were from the AVIRIS-NG imagery acquired on 4 September 2014 (Figure 2, red box). The mean L_t and XCH_4 over the pixel are denoted by L_{t_GOSAT} and XCH_{4_GOSAT} , respectively. Then, using the average albedo for all the subpixels, simulations were carried out by varying XCH_4 to minimize the average residual radiance between the simulated L_t and L_{t_GOSAT} until it was smaller than the band-averaged $NE\delta L$ ($NE\delta L_a$). The error minimized XCH_4 is denoted XCH_{4_M} . It is important to note that XCH_{4_M} was smaller than XCH_{4_GOSAT} . Figure 14 shows the XCH_4 underestimation (γ) with respect to percentage area coverage by the CH_4 plume in a pixel of the same size as GOSAT (P_c). Note the pixel size is fixed while P_c is varied.

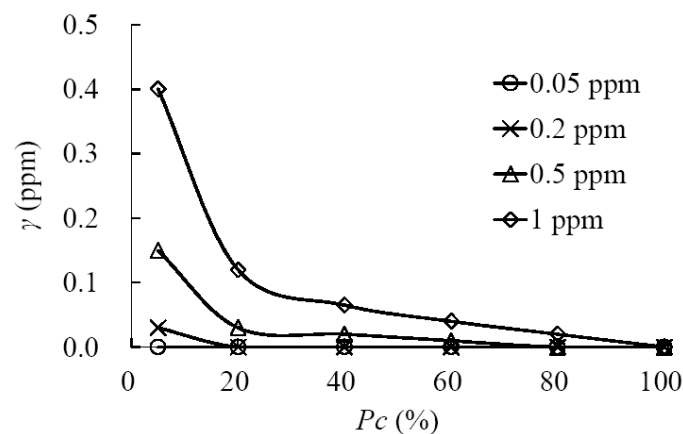


Figure 14. XCH_4 underestimation (γ) with the subpixel percent coverage (P_c) of the GOSAT pixel covered by a CH_4 plume anomalies from 0.05 to 1 ppm, remainder background CH_4 . Data key on figure.

Variations in P_c change for the average XCH_4 . For example, a pixel with the mean $XCH_4 = 0.5$ ppm, a 5% variation of P_c implies that 5% of the 160×160 subpixels were covered by a plume with $XCH_4 = 10$ ppm. In this case, the forward simulation indicates that a XCH_4 of 0.35 ppm can be observed over the pixel (γ is equal to 0.15 ppm). As P_c decreases, γ increases but γ also increases for increasing XCH_4 plume strength, e.g., γ increases from 0.01 to 0.15 ppm when P_c decreases from 60% to 5% for an anomaly of 0.5 ppm. Thus, biases can become significant if the pixel percent coverage by a strong plume is small.

4. Discussion and Conclusions

4.1. Scoping Study

The scoping study identified a surprising difference in performance of the band ratio approach for similar strength sources from the COP marine seep field and for Kern Front oil field (Figure 1). The band ratio approach clearly detected plumes for the marine source, while plumes were not apparent for the terrestrial source. Key differences between these settings include water vapor, aerosol, and surface albedo heterogeneity—often termed spectral clutter.

Using a forward simulation and a residual radiance approach (as in the CH_4 detection algorithm in Roberts et al. [29]), sensitivity of XCH_4 to a variety of factors was investigated. The greatest sensitivity was from surface albedo (Figures 6, A4 and A5). A -5% error in surface albedo could cause a relative error up to 144.3% depending on the CH_4 concentration. Such a strong sensitivity arises from the high percentage of the surface reflected radiance in the total radiance received by AVIRIS-NG. Even a small error in surface albedo requires a large XCH_4 to compensate in the total radiance spectrum. Sensitivity to scene-differing factors other than surface albedo error, such as scene geometry, aerosols, and water vapor was small, although some were important in terms of accurate retrievals. For example, sensitivity to water vapor showed a 9% overestimation of water vapor (equivalent to 1.9 g cm^{-2}) results in a 4.6% overestimation for background XCH_4 . Despite significant differences in aerosol between a marine atmosphere (COP) and a terrestrial atmosphere (Kern Front), aerosol was found to be of negligible importance to the different scene retrieval performances. As a result, the non-albedo sensitivity factors cannot explain the difference in retrieval performance between the scenes.

Surface albedo error also induces uncertainty in retrieved trace gas column in a second manner due to spectral non-flatness. Specifically, the assumption of spectral flatness in Roberts et al. [29] was investigated and found to introduce significant uncertainty in XCH_4 , up to over 100%, depending on the plume strength and the underlying pixel surface type. This spectral factor occurs in synergy with albedo error, and illustrates the importance of accurately retrieving the surface albedo spectra, within and across the CH_4 absorption feature.

Above all, the non-linear sensitivity of XCH_4 to the albedo error could explain most of the difference in the retrieval performance between two different scenes. It should also be noted from Noël et al. (2012) that the distortion of the slit function for an inhomogeneously illuminated slit could also be another reason for the difference in retrieval performance [38].

4.2. In Situ Versus Uniform Profile

The simplest profile is a well-mixed PBL—i.e., uniform with altitude; which was quite distinct from the real profile where concentration decreased rapidly with altitude in the upper PBL, with a sharp decrease above (Figure 3). In the simulations, the column was held the same for the two, to test sensitivity to albedo error, and found a 9–12% increase in albedo error sensitivity. In other words, the realistic profile improved retrieval performance against artifacts resulting from surface albedo error.

4.3. Interferents

Accurate surface albedo is critical to any retrieval method, and this study found it to be highly sensitive for the residual radiance retrieval approach. In part, this non-linearity arose from radiative interaction between water vapor and CH₄ column, both of which depend on surface albedo. Finer spectral resolution would enable better deconvolution of these factors (AVIRIS-NG versus AVIRIS-C), decreasing the albedo error sensitivity. In the limit, extremely fine spectral resolution sensors, e.g., SCHIAMACHY, that resolve individual absorption lines, avoid most of the problems of assumed spectral flatness, which, while potentially significant over tens of nanometers, are minimal across a single line.

4.4. Retrieval Method and Future Work

This sensitivity study used the forward simulation and residual radiance; thus the results are directly applicable only to the residual radiance method for XCH₄ retrieval. As noted above, surface albedo is critical to any retrieval method, particularly if the cluttered surface includes material with spectral features in the wavelengths of the trace gas. For example, carbonates have spectral features in the 2.4 μm CH₄ feature. Thorpe et al. [22], found that the IMAP-DOAS approach, which succeeded at CH₄ retrievals for AVIRIS imagery for the COP seep field, was challenged by retrievals for a terrestrial scene. Specifically, they noted that “disentangling surface spectral signatures from the methane absorption features is complicated”. Some approaches are likely to be less sensitive, such as the singular value decomposition hybrid IMAP-DOAS approach adopted by Thorpe et al. [22] to address complex terrestrial scenes. Higher spatial resolution may or may not reduce sub-pixel element heterogeneity, depending on how the end members are organized spatially. Albedo error uncertainty is largest if the spectral contrast in the absorption feature between end members is large; thus pixels at water/ice-land boundaries present very strong contrasts that will introduce relatively larger uncertainty. Specifically, the different pixel end members introduce positive and negative biases that are non-linear and thus do not cancel when combined to calculate XCH₄ for the pixel. This would not be true if the biases were linear, in which case they would cancel when combined. One approach is to statistically model surface composition outside the plume, as an application for plume pixels. This approach is challenged by non-statistical surfaces such as river banks and urban areas where natural laws do not govern pixel end member component distributions.

These simulations were for a uniform surface; however, many surfaces exhibit complicated BRDF. The importance of realistic scene BRDF should be explored in further studies.

In any case, the fundamental importance of surface albedo to retrievals shows a need for investigating the sensitivity of different retrieval algorithms, to better understand the advantages and limitations of each approach, with respect to different applications. This is particularly important for broad spectral resolution instruments like AVIRIS-C, AVIRIS-NG, and the candidate HypIRI orbital mission, as well as for spectrometers with finer spatial resolution.

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Author Contributions: Ira Leifer designed the research experiment and contributed to the structure, writing, and editing of the manuscript. Chuanmin Hu contributed to editing of the manuscript. Minwei Zhang performed the data analysis, made figures, and wrote the manuscript.

Conflicts of Interest: The authors declare no conflict of interest.

Appendix A

Appendix A.1. In Situ Measurements

The Center for Interdisciplinary Remotely Piloted Aircraft Studies CIRPAS Twin Otter airplane collected airborne in situ greenhouse gas and meteorology data. The CIRPAS standard instrumentation suite includes temperature, 3D winds, humidity, and aerosol. More information on the CIRPAS instrumentation suite is found at www.cirpas.org [39]. Furthermore, in situ airborne measurements were made by a cavity-ringdown spectrometer, which sampled at 10 Hz and provided CH₄ within 0.1 ppm (G-2301f, Picarro Inc., Santa Clara, CA, USA). The Picarro instrument used a direct current (DC)- powered external vacuum pump (N920, KNF Labs, Trenton, NJ, USA) connected to the main air sample inlet port by a 0.46 cm diameter and 3.28 m long PTFE tube. Lab calibrations were performed with gas standards before and after aircraft integration and used to assess instrument stability and develop corrections for drift.

In situ CIRPAS data mapped multiple distinct, strong CH₄ plumes, including several that penetrated above the PBL, as well as a clearly defined and also strong, broad-based plume (Figure A1A). CO₂ plumes were far more localized (vertically and horizontal) than the CH₄ plumes (Figure A1B).

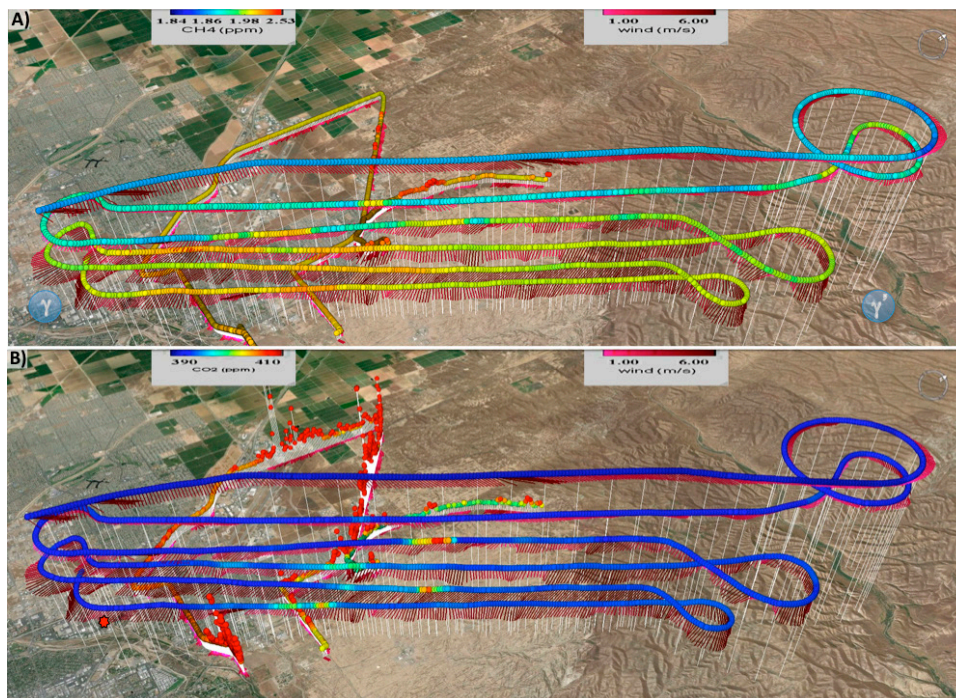


Figure A1. (A) Methane (CH₄) and (B) carbon dioxide (CO₂), and winds for 4 September 2014 from airborne in situ (CIRPAS) and surface mobile in situ (AMOG surveyor). Red star shows data curtain zero point (119.0411°W, 35.3972°N). Data keys on panels.

The anomaly was determined relative to a background concentration (Figure A1), defined as the peak of a best-fit Gaussian function to the concentration probability histogram of each transect at each altitude in the data curtain.

Winds were strongest slightly below the top of the PBL (Figure A2D), where a broad, thin CH₄ plume was observed at ~800–1000 m altitude (Figure A2B). This would be consistent with rising buoyant plumes that were too weak to penetrate above the PBL. Several strong, lower altitude plumes were identified at 500 m altitude, which most likely originated in the near field to the curtain. Subtracting the background concentration field (Figure A2C) yielded the CH₄ anomaly (CH₄') (Figure A2F).

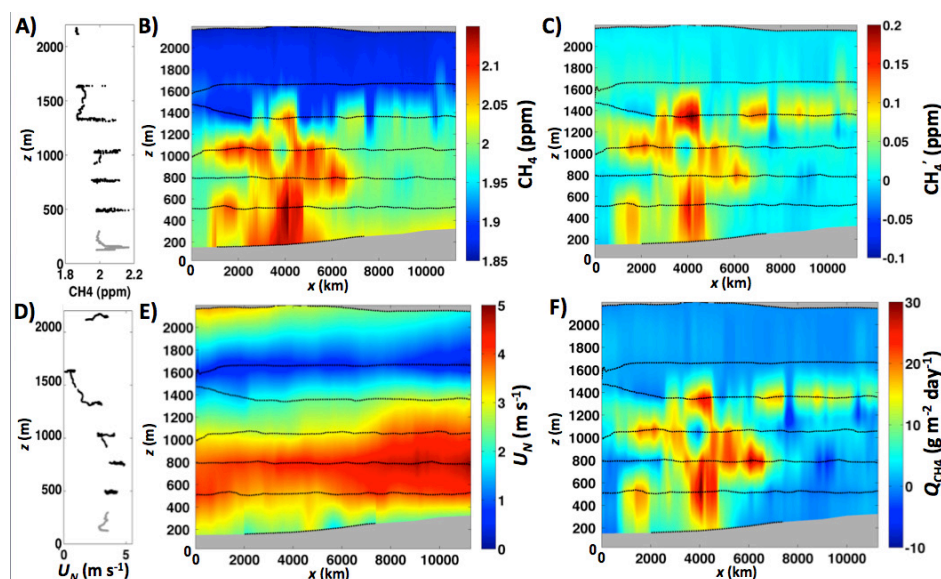


Figure A2. (A) Downwind methane (CH_4) vertical profile with altitude (z) for Kern Front oil field transect (Figure A1) on 4 September 2014, and (B) Transect curtain, vertically-interpolated $\text{CH}_4(x, z)$, where x is easting distance relative to 119.0411°W , 35.3972°N . Dashed line shows data locations with gray for ground and above airborne data. Where surface data were unavailable, surface values were extrapolated from $C_{\text{AMOG}}/C_{\text{CIRPAS}(500\text{ m})}$ and (C) CH_4 anomaly ($\text{CH}_4'(x, z)$) based on background subtraction, (D) plane-normal wind profile ($U_N(z)$), as in panel A, (E) transect curtain $U_N(x, z)$ and (F) transect curtain of CH_4 flux ($Q_{\text{CH}_4}(x, z)$). Data key on panels.

Appendix A.2. Scene Element Selection

FLAASH was applied to the atmospheric correction of AVIRIS-NG data acquired on 4 September 2014, from which we derived surface albedo (q_s). Based on a histogram of occurrence probability, we selected three pixels with surface albedos spanning the dominant scene range albedo range at 2239 nm (CH_4 absorption feature), specifically, 0.19, 0.29, and 0.48 (Figure A3).

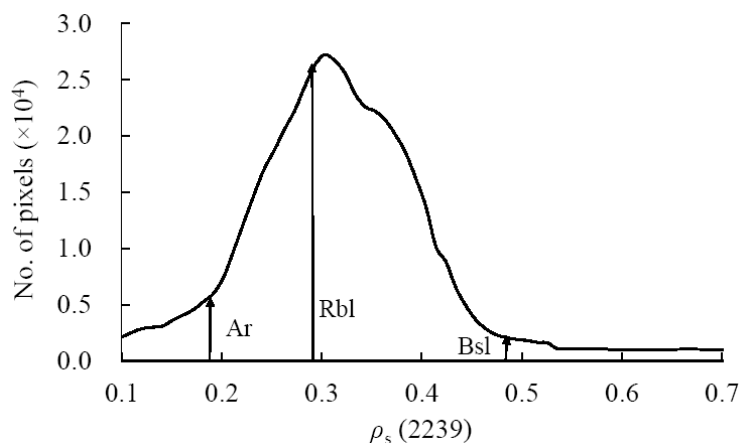


Figure A3. Scene occurrence histogram for surface albedo (q_s) for 2239 nm derived from FLAASH atmospheric correction of AVIRIS-NG data on 4 September 2014. $q_s(2239)$ for the three pixels Asphalt road (Ar), Brown sandy loam (Bsl), and Reddish brown sandy loam (Rbl), identified on figure.

Element pixel occurrence was calculated from a spectral similarity parameter between AVIRIS-NG retrieved q_s and albedo spectra in ENVI spectral library. The parameter combines Euclidean distance with correlation coefficient [40]. The albedo spectra with the smallest similarity parameter among

those in the spectral library were used in the sensitivity simulation. The histogram confirmed that elements with these albedos, Asphalt road, Ar, Brown sandy loam, Bsl, and Reddish-brown sandy loam, Rbl, were in fact common scene elements, with Rbl dominant.

Appendix A.3. Requirement for q_s Accuracy in Terms of Accuracy of GOSAT Retrieved XCH_4

GOSAT-measured XCH_4 is biased low by $1.2 \pm 1.1\%$ compared with the measurements from ground-based high-resolution Fourier Transform Spectrometers in Total Carbon Column Observing Network (TCCON) [41]. The XCH_4 retrieved by means of a proxy method and a physics method is compared with ground-based XCH_4 measurements at 12 stations. The retrieval bias for the proxy method ranges from -0.321% to 0.421% with a standard deviation of 0.22% . The range is from -0.836% to -0.081% and the standard deviation is 0.24% for the physics method [17]. Through accurate O_2A -band modeling, the bias decreases to -0.30% with a standard deviation of the bias about 0.26% [42]. Considering all these validations, 0.5% was selected as the relative error of GOSAT retrieved XCH_4 . Table A1 shows the requirement for the accuracy of surface albedo if the accuracy of AVIRIS-NG retrieved XCH_4 reaches that of GOSAT measured XCH_4 .

Table A1. Minimum requirement for the accuracy of q_s if the accuracy of AVIRIS-NG retrieved XCH_4 reaches that for GOSAT measured XCH_4 .

XCH_4	Relative Error (%)		
	Ar	Rbl	Bsl
$k = 0$	0.065	0.064	0.065
$k = 0.1$	0.073	0.076	0.077
$k = 1$	0.11	0.11	0.12
$k = 10$	0.27	0.27	0.26

Appendix A.4. Accuracy of Remotely Sensed q_s

The sensitivity studies showed a significant sensitivity to surface albedo error in retrieved XCH_4 . We investigated the accuracy of the q_s retrieved from remotely sensed data. An absolute error of 0.02 between MODIS retrieved q_s and in situ data is shown by [43]. Seventy percent of the matchup comparison between MODIS measured and in situ 16-day-averaged q_s from 2001 to 2003 showed an absolute difference of 0.02 [44]. With an assumption that q_s can be retrieved with an absolute error of 0.02 from AVIRIS-NG, the accuracy of AVIRIS-NG retrieved XCH_4 was investigated (Figure A4). The $S(XCH_{4,b}, \alpha)$ resulted from an absolute underestimation of 0.02 in q_s can be over 290% for the pixel Ar with a $XCH_{4,A}$. $S(XCH_{4,b}, \alpha)$ decreases with the increase of q_s and increase of XCH_4 , to 40% for pixel Ar with a XCH_4 plume case of $k = 10$. The $S(XCH_{4,b}, \alpha)$ decreases slightly with the increase of water vapor.

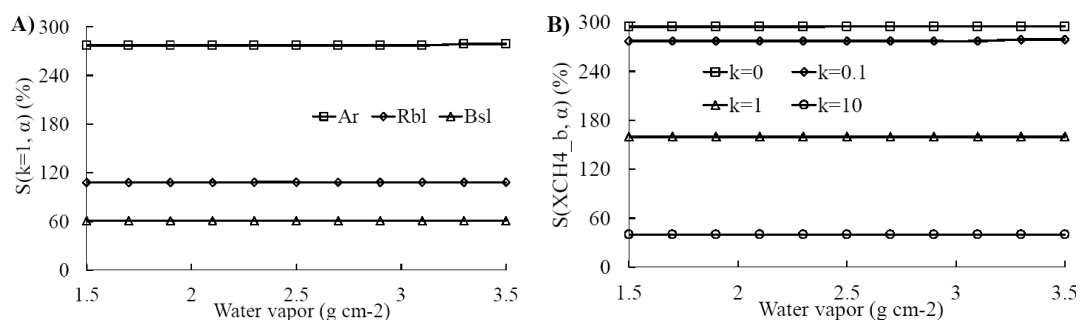


Figure A4. $S(XCH_{4,b}, \alpha)$ resulted from an underestimation of 0.02 in q_s for **A)** three pixels Asphalt road (Ar), Brown sandy loam (Bsl), and Reddish brown sandy loam (Rbl) with the XCH_4 plume case of $k = 0.1$, and **B)** pixel Ar with XCH_4 plume cases of $k = 0, 0.1, 1, 10$.

Appendix A.5. Expected Accuracy of AVIRIS-NG Retrieved XCH_4

Based on the analysis described above, the accuracy of XCH_4 retrieved from a AVIRIS-NG image using the residual radiance method is affected mainly by q_s , although the non-linearity to q_s arises in part from the additive contribution of water vapor column to at sensor radiance. Many algorithms have been developed for retrieving q_s and water vapor from remotely sensed data. The retrieved products have been validated against in situ data, from which the accuracy is derived. With an assumption that q_s and water vapor can be retrieved from AVIRIS-NG imagery with the same accuracy as they are retrieved from remotely sensed data, the expected accuracy for XCH_4 retrieved from AVIRIS-NG using the residual radiance method could be derived. An absolute error of 0.02 and a relative error of 9% were selected for the accuracy of q_s and water vapor, respectively.

Figure A5 shows the $S(XCH_{4_b}, \alpha)$ resulted from a combination of absolute q_s underestimation of 0.02 and a relative water vapor column overestimation of 9%. The expected accuracy of the XCH_4 increases with the increase of XCH_4 and the surface albedo. $S(XCH_{4_b}, \alpha)$ is only weakly relate to water vapor column. It should be noted that accuracy is derived without considering the uncertainty in the AVIRIS-NG radiometric calibration and for an assumed $NE\delta L = 0.00035 \text{ mW cm}^{-2} \mu\text{m}^{-1} \text{ sr}^{-1}$. Corrected sensitivities can be derived for improved estimates of uncertainty and $NE\delta L$.

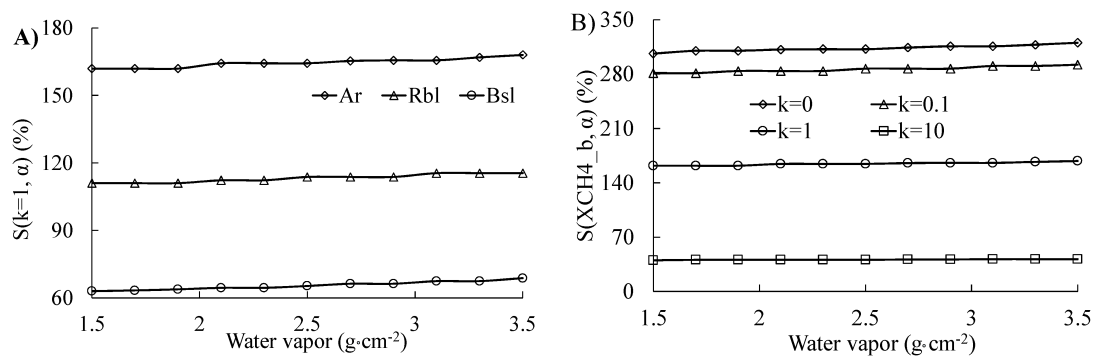


Figure A5. $S(XCH_{4_b}, \alpha)$ resulted from a combination of an absolute underestimation of 0.02 in q_s and a relative overestimation of 9% in column water vapor for (A) three pixels Asphalt road (Ar), Brown sandy loam (Bsl), and Reddish brown sandy loam (Rbl) with the XCH_4 plume case of $k = 1$, and (B) the pixel Ar with XCH_4 plume cases of $k = 0, 0.1, 1, 10$.

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